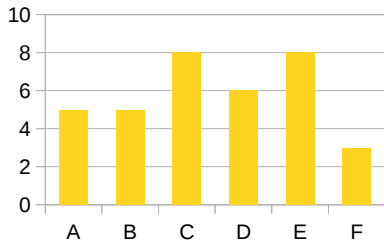
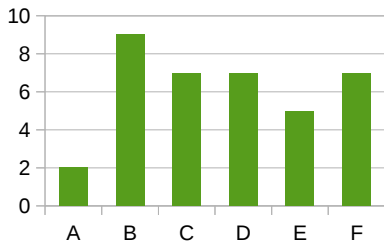
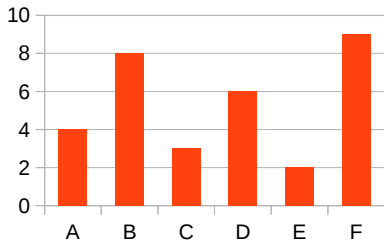
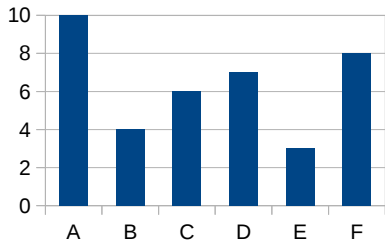


An introduction to robust combinatorial optimization

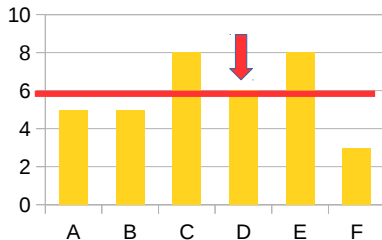
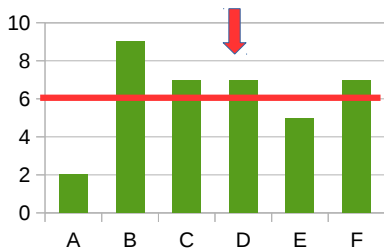
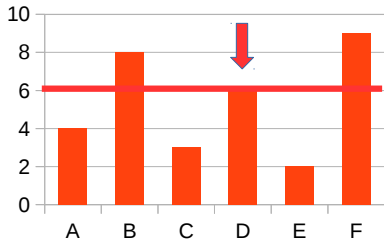
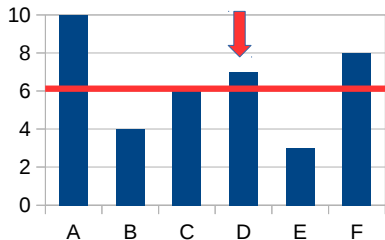
Michael Poss

October 18, 2022

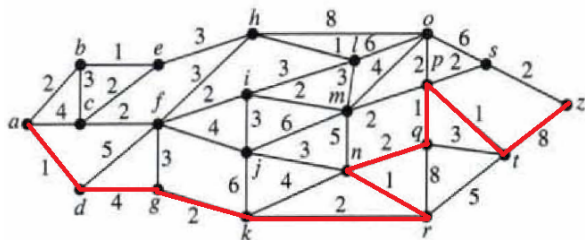
Optimality: criterion max min (or min max)



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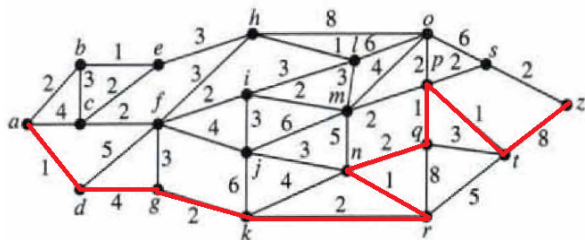
Feasibility: all scenarios matter



Like shortest path but with 2 resources

- Cost
- Time $\leq C \Leftrightarrow \sum_{a \in \mathcal{P}} u_a \leq C \forall u \in \mathcal{U}$

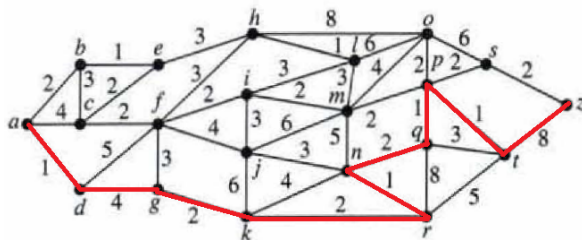
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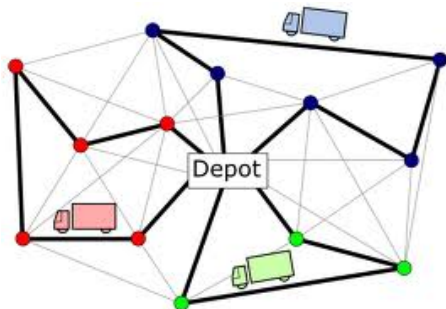
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Vehicle routing problem



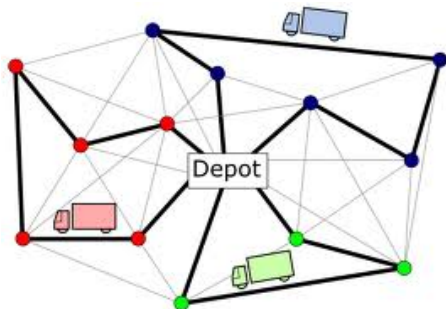
Different robust counterparts:

- Cost uncertainty
- Demand uncertainty:

$$\sum_{i \in \text{route}} u_i \leq \text{Capacity}, \quad \forall u \in \mathcal{U}, \text{route} \in \text{Routes}$$

- Travel time uncertainty

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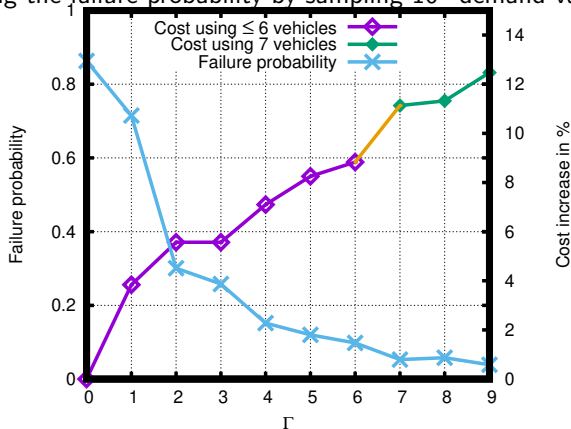
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Numerical example with demand uncertainty

- A company needs to be pick up packages of uncertain dimensions
- The company owns 6 vehicles
- Possibility of renting an additional vehicle
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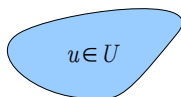


How much do we know ?

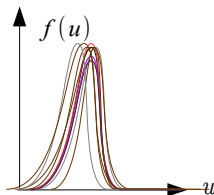
Mean value
(Deterministic)

• $\mathbf{E}[u]$

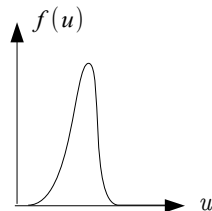
Robust



Distributionally
robust



Stochastic



Static decisions \rightarrow uncertainty revealed

Complexity Easy for LP 😊, \mathcal{NP} -hard for combinatorial optimization 😞
MILP reformulation 😊

Two-stages decisions \rightarrow uncertainty revealed \rightarrow more decisions

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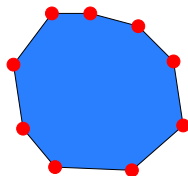
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$$\mathcal{U} = \text{vertices}(\mathcal{P})$$



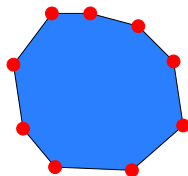
Observation

In many cases, $\mathcal{U} \sim \mathcal{P}$.

Exceptions:

- robust constraints $f(x, u) \leq b$ and f non-concave in u
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Robust combinatorial optimization

Combinatorial problem

- $\mathcal{X} \subseteq \{0, 1\}^n, u_0 \in \mathbb{R}^n$

$$CO \quad \min_{x \in \mathcal{X}} u_0^T x.$$

Robust counterparts with cost uncertainty

- $\mathcal{X} \subseteq \{0, 1\}^n, \mathcal{U} \subset \mathbb{R}^n$

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- Regret version:

$$\min_{x \in \mathcal{X}} \max_{u \in \mathcal{U}} \left(\overbrace{u^T x}^{f(x)} - \min_{y \in \mathcal{X}} u^T y \right)$$
$$\min_{x \in \mathcal{X}} \max_{u \in \mathcal{U}} (u^T x - u^T y)$$

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General robust counterpart

$$\mathcal{X} = \mathcal{X}^{comb} \cap \mathcal{X}^{num} :$$

\mathcal{X}^{comb} Combinatorial nature, **known**.

\mathcal{X}^{num} Numerical uncertainty: $u_j^T x \leq b_j, j = 1, \dots, m$, **uncertain**.

Example (Vehicle routing)

\mathcal{X}^{comb} routes in the graph

\mathcal{X}^{num} demand cannot exceed the capacity

Robust counterpart

$$\min \left\{ \begin{array}{l} \max_{u_0 \in \mathcal{U}_0} u_0^T x : \end{array} \right. \quad (1)$$

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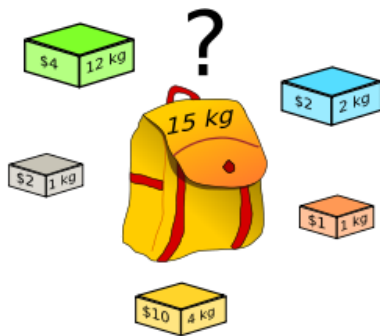
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Knapsack problem



How to maximize profit without violating the knapsack capacity?

Deterministic situation

profit p , weight u , capacity C

$$\begin{aligned} \max \quad & \sum_{i \in N} p_i x_i \\ \text{s.t.} \quad & \sum_{i \in N} u_i x_i \leq C \\ & x \in \{0, 1\}^{|N|}. \end{aligned}$$

- \mathcal{NP} -hard in the weak sense: difficult, but not too much.
- Arizes in vehicle routing, facility location, network design, assignment problems, investment problems, ...

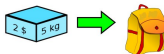
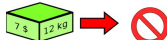
Uncertainty

- 5 items, capacity = 15
- Scenario $k \Rightarrow u_k \times \frac{4}{3}$

Data



Deterministic solution



$$\begin{aligned}
 \max \quad & 10x_1 + 7x_2 + x_3 + 3x_4 + 2x_5 \\
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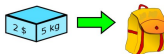
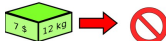
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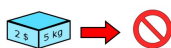
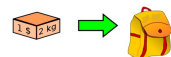
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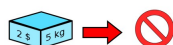
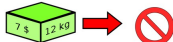
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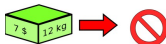
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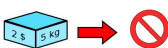
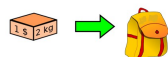
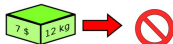
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discrete uncertainty: \mathcal{U} -CO is hard [Kouvelis and Yu, 2013]

Theorem

The robust shortest path, assignment, spanning tree, ... are \mathcal{NP} -hard even when $|\mathcal{U}| = 2$.

Proof.

- 1 SELECTION PROBLEM: $\min_{S \subseteq N, |S|=p} \sum_{i \in S} u_i$
- 2 ROBUST SEL. PROB.: $\min_{S \subseteq N, |S|=p} \max_{u \in \mathcal{U}} \sum_{i \in S} u_i$
- 3 PARTITION PROBLEM: $\min_{S \subseteq N, |S|=|N|/2} \max \left(\sum_{i \in S} a_i, \sum_{i \in N \setminus S} a_i \right)$
- 4 Reduction: $p = \lfloor \frac{|N|}{2} \rfloor$, and $\mathcal{U} = \{u^1, u^2\}$ such that

$$u_i^1 = a_i \quad \text{and} \quad u_i^2 = \frac{2}{|N|} \sum_k a_k - a_i$$

$$\Rightarrow \max_{u \in \mathcal{U}} \sum_{i \in S} u_i = \max \left(\sum_{i \in S} a_i, \sum_{i \in N \setminus S} a_i \right)$$

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$$\Rightarrow \max_{u \in \mathcal{U}} \sum_{i \in S} u_i = \max \left(\sum_{i \in S} a_i, \sum_{i \in N \setminus S} a_i \right)$$

discrete uncertainty: \mathcal{U} -CO is hard [Kouvelis and Yu, 2013]

Theorem

The robust shortest path, assignment, spanning tree, ... are \mathcal{NP} -hard even when $|\mathcal{U}| = 2$.

Proof.

- 1 SELECTION PROBLEM: $\min_{S \subseteq N, |S|=p} \sum_{i \in S} u_i$
- 2 ROBUST SEL. PROB.: $\min_{S \subseteq N, |S|=p} \max_{u \in \mathcal{U}} \sum_{i \in S} u_i$
- 3 PARTITION PROBLEM: $\min_{S \subseteq N, |S|=|N|/2} \max \left(\sum_{i \in S} a_i, \sum_{i \in N \setminus S} a_i \right)$
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polyhedral uncertainty: \mathcal{U} -CO is still hard (but solvable)

Theorem (Kouvelis and Yu [2013])

The robust shortest path, assignment, spanning tree, ... are \mathcal{NP} -hard even when \mathcal{U} has a compact description.

Proof.

- 1 $u^T x \leq b, u \in \mathcal{U} \Leftrightarrow u^T x \leq b, u \in \text{ext}(\mathcal{U})$
- 2 $\mathcal{U} = \text{conv}(u^1, u^2) \Rightarrow n$ equalities and 2 inequalities



Theorem (Dualization - Ben-Tal and Nemirovski [1998])

Problem \mathcal{U} -CO is equivalent to a mixed-integer linear program.

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Dualization - cost uncertainty

Theorem (Ben-Tal and Nemirovski [1998])

Consider $\alpha \in \mathbb{R}^{l \times n}$ and $\beta \in \mathbb{R}^l$ that define polytope

$$\mathcal{U} := \{u \in \mathbb{R}_+^n : \alpha_k^T u \leq \beta_k, k = 1, \dots, l\}.$$

Problem $\min_{x \in \mathcal{X}} \max_{u \in \mathcal{U}} u^T x$ is equivalent to a compact MILP.

Proof.

Dualizing the inner maximization:

$$\begin{aligned} \min_{x \in \mathcal{X}} \max_{u \in \mathcal{U}} u^T x &= \min_{x \in \mathcal{X}} \min \left\{ \sum_{k=1}^l \beta_k z_k : \sum_{k=1}^l \alpha_{ki} z_k \geq x_i, i = 1, \dots, n, z \geq 0 \right\} \\ &= \min \left\{ \sum_{k=1}^l \beta_k z_k : \sum_{k=1}^l \alpha_{ki} z_k \geq x_i, i = 1, \dots, n, z \geq 0, x \in \mathcal{X} \right\} \end{aligned}$$

Dualization example

Can also be applied to robust constraints!

Example (Static problem)

$$\begin{aligned} \max \quad & 3x_1 + 5x_2 + 9x_3 \\ \text{s.t.} \quad & u_1x_1 + u_2x_2 + u_3x_3 \leq 8 \quad \forall u \in \mathcal{U} \\ & x \in \{0, 1\}^3. \end{aligned}$$

Example (Uncertainty polytope)

$$\mathcal{U} \equiv \left\{ \begin{array}{l} 3u_1 + u_2 + u_3 \leq 10 \\ u_1 + 2u_2 \leq 8 \\ u_1 + 2u_3 \leq 7 \\ u_2 + u_3 \leq 5 \\ u_1, u_2, u_3 \geq 0 \end{array} \right. \left. \begin{array}{l} [z_1] \\ [z_2] \\ [z_3] \\ [z_4] \end{array} \right\}$$

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The static problem is equivalent to:

$$\begin{aligned} \max \quad & 3x_1 + 5x_2 + 9x_3 \\ \text{s.t.} \quad & 10z_1 + 8z_2 + 7z_3 + 5z_4 \leq 8 \\ & 3z_1 + z_2 + z_3 + z_4 \geq x_1 \\ & z_1 + 2z_2 \geq x_2 \\ & z_1 + 2z_3 + z_4 \geq x_3 \\ & x \in \{0, 1\}^3, z \geq 0. \end{aligned}$$

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Cutting plane algorithms [Bertsimas et al., 2016]

$$\mathcal{U}_0^* \subset \mathcal{U}_0, \mathcal{U}_j^* \subset \mathcal{U}_j$$

Master problem

$$MP \quad \min \left\{ \begin{array}{l} z : \\ u_j^T x \leq b_j, \quad j = 1, \dots, m, \quad u_j \in \mathcal{U}_j^*, \\ u_0^T x \leq z, \quad u_0 \in \mathcal{U}_0^*, \\ a_k^T x \leq d_k, \quad k = 1, \dots, \ell \\ x \in \{0, 1\}^n \end{array} \right\}$$

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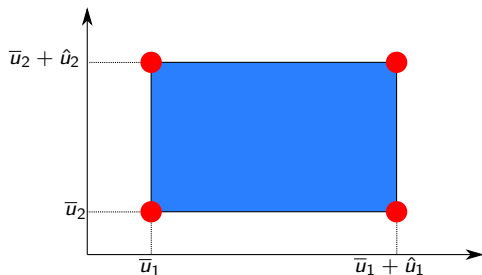
Simpler structure: \mathcal{U}^Γ -robust combinatorial optimization

- \mathcal{U} = vertices(\mathcal{P}): good, but need “simpler” \mathcal{P}

$$\mathcal{U}^\Gamma = \left\{ \bar{u}_i \leq u_i \leq \bar{u}_i + \hat{u}_i, i = 1, \dots, n, \sum_{i=1}^n \frac{u_i - \bar{u}_i}{\hat{u}_i} \leq \right\}$$

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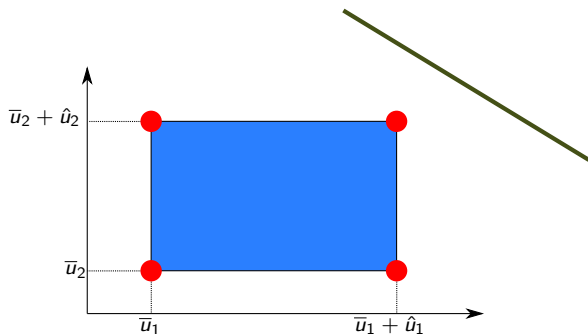
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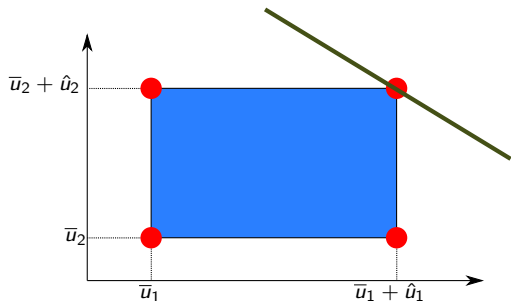
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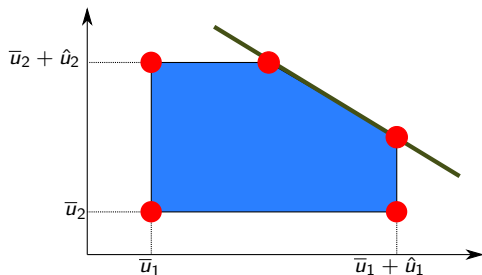
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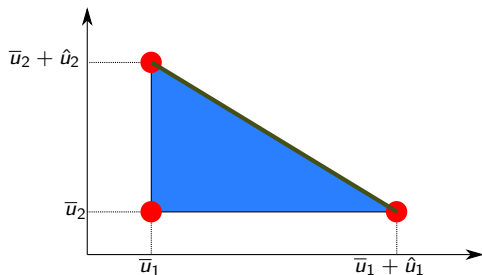
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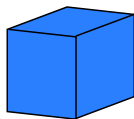
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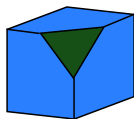
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Iterative algorithms for \mathcal{U}^Γ

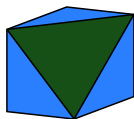
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$\Gamma = 3$



$\Gamma = 2.5$



$\Gamma = 2$

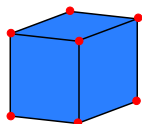
Theorem (Bertsimas and Sim [2003], Goetzmann et al. [2011],
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Cost uncertainty \mathcal{U}^Γ -CO \Rightarrow solving $\sim n + 1$ problems CO.

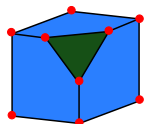
Numerical uncertainty \mathcal{U}^Γ -CO \Rightarrow solving $\sim (n + 1)^m$ problems CO.

Iterative algorithms for \mathcal{U}^Γ

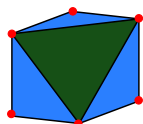
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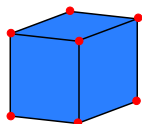
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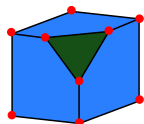
Numerical uncertainty \mathcal{U}^Γ -CO \Rightarrow solving $\sim (n + 1)^m$ problems CO.

Iterative algorithms for \mathcal{U}^Γ

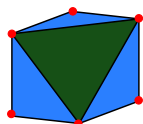
$$\mathcal{U}^\Gamma = \text{vertices} \left(\left\{ \bar{u}_i \leq u_i \leq \bar{u}_i + \hat{u}_i, i = 1, \dots, n, \sum_{i=1}^n \frac{u_i - \bar{u}_i}{\hat{u}_i} \leq \Gamma \right\} \right)$$



$\Gamma = 3$



$\Gamma = 2.5$



$\Gamma = 2$

Theorem (Bertsimas and Sim [2003], Goetzmann et al. [2011],
Álvarez-Miranda et al. [2013], Lee and Kwon [2014])

Cost uncertainty \mathcal{U}^Γ -CO \Rightarrow solving $\sim n + 1$ problems CO.

Numerical uncertainty \mathcal{U}^Γ -CO \Rightarrow solving $\sim (n + 1)^m$ problems CO.

Example

$$\Gamma \hat{u}_\ell + \min_{x \in \mathcal{X}} \sum_i (\bar{u}_i + [\hat{u}_i - \hat{u}_\ell]^+) x_i$$

Example (Static problem)

$$\begin{aligned} \max \quad & 3x_1 + 5x_2 + 9x_3 \\ \text{s.t.} \quad & u_1x_1 + u_2x_2 + u_3x_3 \leq 8 \quad \forall u \in \mathcal{U}^\Gamma \\ & x \in \{0, 1\}^3. \end{aligned}$$

Example (Uncertainty polytope)

$$\mathcal{U}^\Gamma \equiv \left\{ \begin{array}{l} 3 \leq u_1 \leq 3 + 1 \\ 2 \leq u_2 \leq 2 + 2 \\ 1 \leq u_3 \leq 1 + 4 \\ \frac{u_1 - 3}{1} + \frac{u_2 - 2}{2} + \frac{u_3 - 1}{4} \leq 1 \end{array} \right\}$$

Example (Solution algorithm)

Solve 4 knapsack problems

$$\begin{aligned} \max \quad & 3x_1 + 5x_2 + 9x_3 \\ (\hat{u}_\ell = 0) \quad \text{s.t.} \quad & 4x_1 + 4x_2 + 5x_3 \leq 8 \\ & x \in \{0, 1\}^3. \end{aligned}$$

$$\begin{aligned} \max \quad & 3x_1 + 5x_2 + 9x_3 \\ (\hat{u}_\ell = 1) \quad \text{s.t.} \quad & 3x_1 + 3x_2 + 4x_3 \leq 7 \\ & x \in \{0, 1\}^3. \end{aligned}$$

$$\begin{aligned} \max \quad & 3x_1 + 5x_2 + 9x_3 \\ (\hat{u}_\ell = 2) \quad \text{s.t.} \quad & 3x_1 + 2x_2 + 3x_3 \leq 6 \\ & x \in \{0, 1\}^3. \end{aligned}$$

$$\begin{aligned} \max \quad & 3x_1 + 5x_2 + 9x_3 \\ (\hat{u}_\ell = 4) \quad \text{s.t.} \quad & 3x_1 + 2x_2 + 1x_3 \leq 5 \\ & x \in \{0, 1\}^3. \end{aligned}$$

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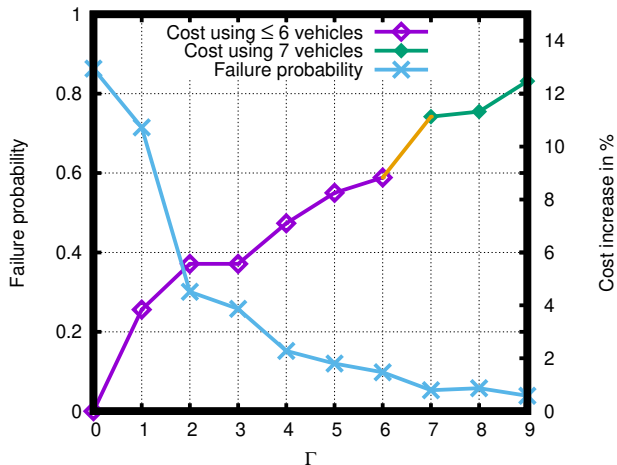
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\mathcal{U}^Γ : example

- Need to specify \bar{u} , \hat{u} , and Γ
- Example: $\bar{u} = \mu$ and $\hat{u} = \sigma$



Vehicle Routing Problem (CVRP) - Compact formulation

x_{ij}^k vehicle k uses arc (i, j) ?
 u_i uncertain demand at node i

$$\begin{aligned} \min \quad & \sum_{i,j} c_{ij} x_{ij}^k \\ \text{s.t.} \quad & \text{flow conservation} \\ & \text{cycle-breaking} \\ & \sum_{i,j} u_i x_{ij}^k \leq C, \quad \forall k \in K, u \in U \\ & x \text{ binary} \end{aligned}$$

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Iterative algorithm

$|K|$ capacity constraints $\Rightarrow (n+1)^{|K|}$
nominal problems to be solved!

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Vehicle Routing Problem (CVRP) - Set-partition

x_r^k vehicle k uses route r ?

$$\begin{aligned} \min \quad & \sum_{r,k} c_r x_r^k \\ \text{s.t.} \quad & \sum_{r:i \in r} x_r^k = 1, \quad \forall i \in V \\ & x \text{ binary} \end{aligned}$$

Pricing problem

x_{ij} new route uses arc (i, j) ?

u_i uncertain demand at node i

$$\begin{aligned} \min \quad & \sum_{i,j} \kappa_{ij} x_{ij} \\ \text{s.t.} \quad & \sum_{i,j} u_i x_{ij} \leq C, \quad \forall u \in U \\ & x \text{ is a route} \end{aligned}$$

Dualization

$$\begin{aligned} \min \quad & \sum_{i,j} \kappa_{ij} x_{ij} \\ \text{s.t.} \quad & \Gamma z + \sum_i y_i \leq C \\ & z + y_i \geq \sum_j x_{ij}, \quad \forall i \in V \\ & y, z \geq 0 \\ & x \text{ is a route} \end{aligned}$$

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Only 1 capacity constraint $\Rightarrow n + 1$ nominal problems to be solved!

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Examples of numerical results (CVRP)

In. cls	# in.	Iterative algo			Dualization and strengthening		
		#n.	t.	#opt.	gap	t.	#opt.
A	26	1.00	2.91	26	1.97%	3440.31	12
B	23	1.05	5.98	23	1.39%	250.96	13
E	11	1.00	11.40	11	2.19%	573.01	5
F	3	5.37	833.42	2	1.10%	55.76	2
M	3	3.33	153.51	3	2.70%	86700.00	1
P	24	1.00	1.48	24	2.09%	976.36	10
all	90	1.11	4.75	89	1.87%	981.90	43

Are all problems easy?

Hard problems must have one of

- 1 non-constant number of robust “linear” constraints
- 2 “non-linear” constraints/cost function

Theorem (Pessoa et al. [2015])

\mathcal{U}^{Γ} -robust shortest path with time windows is \mathcal{NP} -hard in the strong sense.

Theorem (Bougeret et al. [2016])

Minimizing the weighted sum of completion times is \mathcal{NP} -hard in the strong sense.

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Dualization

good easy to apply

bad breaks combinatorial structure (e.g. shortest path)

Cutting plane algorithms (branch-and-cut)

good handle non-linear functions

bad implementation effort

Iterative algorithms

good good theoretical bounds

bad solving n^s problems can be too much

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- Decision rules (multi-stage setting): Ayse Nur Arslan (Roadef 2022)
Available on youtube
- Modelling: Boris Detienne (Roadef 2020)
Available on video.umontpellier.fr

- With classical publishers, either
 - papers are behind an (expensive) paywall;
 - or authors pay ($\pm 2k$) for Open Access (the so-called **gold** OA)
- OJMO provides a **free** OA alternative (thanks to Mersenne)
- Papers have doi, indexed in [Scopus](#), [DBLP](#), [zbMATH](#), [Crossref](#), ...

Area Editors

- **Continuous Optimization** - David Russell Luke
- **Discrete Optimization** - Sebastian Pokutta
- **Optimization under Uncertainty** - Guzin Bayraksan
- **Computational aspects and applications** - Michael Poss

17 published papers, 13 under review, 73 submissions ... and one prize!

2021 Beale — Orchard-Hays Prize Citation

Alberto Costa and Giacomo Nannicini

"RBFOpt: an open-source library for black-box optimization with costly function evaluations"
Mathematical Programming Computation 10 (2018) 597-629.

"On the implementation of a global optimization method for mixed-variable problems"

[Open Journal of Mathematical Optimization 2 \(2021\).](#)

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